Dhieddine BARHOUMI

Machine learning Engineer

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PROFESSIONAL SUMMARY

Machine Learning Engineer specializing in computer vision and autonomous systems, with hands-on experience in developing AI solutions for security, industrial automation, and autonomous driving. Proven expertise in optimizing deep learning models, implementing sensor fusion systems, and deploying production-ready AI applications. Demonstrated success in reducing system response times by 40% and improving model accuracy by up to 20% in real-world applications.

EDUCATION

National Engineer's Degree in Computer Science National Institute of Applied Sciences and Technology (INSAT) Relevant Courses: Linear Algebra, Database Management, Algorithms and Data Structures, Deep Learning, NLP, Cloud Computing, Big Data, Optimization Methods, Reinforcement Learning

Scientific Baccalaureate

Pioneer High School Hammam-Lif

Top 5% of bachelors with an excellent average grade.

EXPERIENCE

AI Research Intern

Institute For Machine Learning And Analytics (Hochschule Offenburg)

- Selected as a DAAD KOSPIE Scholar for advanced AI research in autonomous driving.
- Developed sensor fusion models integrating LiDAR and cameras for enhanced perception.
- Implemented transformer-based deep learning to improve scene understanding.
- Simulated AI-driven perception in CARLA, refining models before real-world testing.
- Optimized multi-modal pipelines for better AI performance across diverse driving conditions.
- Trained and fine-tuned AI models using high-performance GPUs for real-time processing.
- Upon completion of this six-month internship, I will graduate.
- Skills: Sensor Fusion, Deep Learning, Transformers, CARLA, ROS2, PyTorch, Computer Vision, AI Optimization

Al in Security Systems Intern *All Points Smart Solutions*

- Designed and implemented advanced AI security systems for historic sites including Ajloun Castle and Amman Citadel, enhancing real-time threat detection capabilities and reducing response time to incidents by 40%.
- Enhanced ANPR Accuracy by 20%, optimizing recognition for high-speed and low-light conditions on major streets in Amman.
- Integrated AI Models with Milestone VMS for intelligent object detection and motion tracking, automating alerts and cutting false alarms by 30%
- Tested AI Surveillance Solutions for diverse environments, refining system adaptability.
- Adapted to International Work Environment, gaining experience in cross-cultural collaboration and project execution.
- Skills: AI Surveillance, ANPR, Computer Vision, Deep Learning, Python, Project Coordination, Resource Management

Computer Vision Intern

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- Conducted research on multiple computer vision algorithms, choosing YOLOv8 for optimal speed and accuracy.
- Fine-tuned YOLOv8 for detecting angle and gusset objects in boxes, achieving 92.5% precision and 60% mAP50-95.
- Deployed the model as a real-time API on Microsoft Azure, integrating it with a dashboard for defect detection.
- Automated quality control, triggering alerts for misaligned or missing objects as boxes moved on a conveyor.
- Collaborated with a multidisciplinary team to replace manual defect detection for an industry client, boosting efficiency by 30%.
- Completed Microsoft Azure AI Fundamentals training and certification during the internship.
- Skills: YOLOv8, Computer Vision, Microsoft Azure, API Development, Real-Time Systems, TensorFlow, Python

PROJECTS

AI-Powered Loan Approval System

- Developed a scalable machine learning application for real-time loan approval decisions.
- Designed an end-to-end pipeline including data ingestion, transformation, and model training with hyperparameter tuning.
- Implemented custom utilities, logging, and exception handling for efficient debugging and streamlined operations.
- Dockerized the application and hosted it on Azure Container Registry for scalable cloud deployment.
- Automated CI/CD processes with GitHub Actions, ensuring seamless integration and deployment to Azure Web App Service.
- Skills: Flask, Microsoft Azure, Docker, GitHub Actions, CI/CD, Hyperparameter Tuning

Reinforcement Learning-based Robot Navigation

- Designed a reinforcement learning-based system to navigate complex indoor environments.
- Simulated realistic home-like environments in Gazebo with dynamic obstacles.
- Leveraged ROS2 for seamless integration, utilizing RViz for real-time monitoring of the robot's path and sensor data.
- Collaborated with colleagues, employing GitHub for CI/CD, ensuring robust version control and seamless updates.
- Implemented the TD3 algorithm with a custom reward function to optimize path planning and obstacle avoidance.
- Skills: Reinforcement Learning, ROS2, RViz, Gazebo, TD3, Python, GitHub, CI/CD, Simulation Environments

September. 2020 - Present Tunis, TN

September. 2017 - June 2020 Ben Arous, TN

March. 2025 – August. 2025 Offenburg, DE

June. 2024 - August. 2024

June. 2023 - July. 2023

October. 2024 - November. 2024

September. 2023 - December. 2023

Ben Arous, TN

Amman, JO

TECHNICAL SKILLS

Programming Languages: Python, C++, Java, SQL AI/ML Frameworks: PyTorch, TensorFlow, Keras, scikit-learn, LangChain, Transformers Computer Vision: YOLO, OpenCV, Image Processing, Object Detection, Semantic Segmentation Deep Learning: CNNs, RNNs, Transformers, GANs, Transfer Learning, Fine-tuning MLOps & Cloud: Docker, Kubernetes, CI/CD, Git, Google Cloud Platform, Azure ML, Vertex Al Robotics: ROS2, CARLA, Gazebo, RViz, Sensor Fusion, Path Planning

CERTIFICATIONS

Professional Machine Learning Engineer (Google Cloud) TensorFlow Professional Developer (DeepLearning.AI) Deep Learning Specialization (DeepLearning.AI) AI Engineering Professional Certificate (IBM) AI Fundamentals (Microsoft Azure)

LANGUAGES

English: Professional Working Proficiency (TOEIC C1: 965/990) French: Professional Working Proficiency German: Pre-Intermediate Arabic: Native Proficiency October. 2024 February. 2024 October. 2023 July. 2023 June. 2023